Nuclear Propelled Vessels and Neutrino Oscillation Experiments

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We study the effect of naval nuclear reactors on the study of neutrino oscillations. We find that the presence of naval reactors at unknown locations and times may limit the accuracy of future very long baseline reactor-based neutrino oscillation experiments. At the same time, we argue that a nuclear powered surface ship such as a large Russian icebreaker may provide an ideal source for precision experiments.

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Reactor-based neutrino oscillation experiments [1] have recently generated renewed interest because of their ability to probe very small $\Delta m^2$ values albeit with modest $\sin^22\theta$ sensitivity. The $\sim 1$ km baseline experiments at the Chooz [2] and Palo Verde [3] reactors were optimized for the $10^{-3}$ eV$^2 \leq \Delta m^2 \leq 10^{-2}$ eV$^2$ region and the large mixing angle suggested by the atmospheric neutrino anomaly [4]. The negative results from these two experiments contributed to the elimination of $\nu_e$ as a main component of the atmospheric neutrino signal. The KamLAND experiment [5], now taking data, was designed with a $\approx 200$ km baseline, making it sensitive to the oscillation parameters in the Mikeyev-Smirnov-Wolfenstein large mixing angle solution (MSW-LMA) to the solar neutrino problem [6]. In addition the BOREXINO detector [7], although designed to detect the $^{7}$Be neutrinos from the sun, might also perform oscillation measurements using European reactors [8].

In the future, the interest for reactor-based neutrino oscillation experiments may shift toward the possibility of performing precision measurements. A proposal has been put forward [9] to improve the measurement of $\sin^22\theta_{13}$ beyond the $\sim 0.1$ sensitivity of Chooz and Palo Verde with a high statistics, $\sim 1$ km baseline (double) detector. If the MSW solution is confirmed, depending on the $\Delta m^2$ value found by KamLAND, it may be appropriate to build either a larger detector ($\sim 10$–20 kton) with a similar baseline [10] or a somewhat smaller detector with a $\sim 10$–20 km baseline [11,12] to perform precision measurements.

Very little attention has been given, until now, to the background due to nuclear propelled vessels to these experiments. Although we estimate that the total thermal power generated by such vessels is just a few percent of the total nuclear thermal power in the world, we will show that the mobility and stealthy nature of these installations may produce backgrounds for the present generation experiments. In the case of future detectors, awareness of the background from naval reactors and careful geographical placement will be essential to retain the ability to perform meaningful measurements.

It is also interesting to consider whether this apparent liability could be turned into an asset, by placing the detector far away from any fixed nuclear installations and bringing in a reactor on a vessel. The variable baseline available this way would be important to cancel most systematics and tune the experiment to some particular set of oscillation parameters. In addition, in the case of a very large detector, removing the reactor altogether would allow for lower backgrounds in the study of geological [13] and astrophysical neutrinos.

Naval reactors are mainly installed in submarines, providing underwater endurance and larger power density than conventional engines. Many aircraft carriers and a few other large military vessels are also nuclear powered. While, in general, nuclear propulsion for civilian vessels has only reached the demonstration stage, a notable exception is represented by the Russian fleet of large icebreakers that today counts some seven operational ships. Also in this case the large amount of power and the endurance make nuclear propulsion particularly appropriate for forcing routes through the northern coast of Siberia.

While many details of the design and operation of naval reactors are not available in the open literature, for the purpose of this Letter it will be sufficient to consider the thermal power and, in some cases, a crude estimate of the fuel composition, parameters that are available at least for some reactor types. Typical thermal powers are available for Russian vessels [14] and can be estimated from the quoted “shaft power” [15] for American aircraft carriers assuming a thermodynamical yield of 30% from thermal power to mechanical (shaft) power. In order to estimate the backgrounds from naval reactors to existing experiments, we will consider a “Typhoon” class Russian submarine to transit in the closest tract of sea to KamLAND (Toyama Bay, Sea of Japan) and BOREXINO (Adriatic Sea). In addition, we will consider the effect on these experiments of a U.S. aircraft carrier entering a large military harbor, such as there exist both in Japan (Yokosuka) and Italy (Naples). Typhoons are some of the largest submarines ever built. They are propelled by two reactors with total power of...
0.38 GW_{th}. While other subs have lower power (and often one reactor only), we will use 0.38 GW_{th} as an upper limit for power installed in submarines. As far as we know, both the Sea of Japan and the Adriatic are possibly visited by Russian and/or western submarines for unknown periods and at unknown times.

As discussed above, we can calculate that the USS Enterprise uses ~0.84 GW_{th} for propulsion, generated by two of its eight reactors. Possibly another reactor (and ~0.42 GW_{th}) is used to produce steam for the catapults launching aircraft. Other U.S. carriers have marginally lower power. At least in principle, these ships are easy to detect and their location is not kept secret, so we will not examine the case of one such ship transiting close to shore at the point of closest approach to the experiments (however, we point out that at present no experiment is keeping track of the whereabouts of such ships). To estimate an order of magnitude for the background, we will simply assume that one of these ships, with only the propulsion power of ~0.84 GW_{th}, is in transit at Yokosuka or Naples. Although presumably ships do not enter harbors at full power, the number of surface and submarine ships at these two locations is probably larger than 1 at any given time.

A comparison between the signal from fixed reactors and the background from naval reactors is given in Table I. For simplicity, the flux and count rates from naval reactors have been estimated by assuming the same antineutrino spectrum produced by stationary power reactors. Differences in fuel composition, which will be discussed later, do not alter appreciably the situation.

 Keeping in mind that systematics of at least 2%–3% have to be expected in experiments of this kind [1], it is clear from Table I that the effect of nuclear vessels is not very important at KamLAND, although some method will have to be devised to assign a systematic. The situation is already somewhat different for BOREXINO, in which case a reliable estimate of this systematic error appears essential and rather difficult. While our estimate represents a worst-case scenario and, of course, we are not aware of any quantitative procedure to derive solid systematic errors due to the effects discussed here, the possible presence of naval reactors seems even more problematic for future experiments that might be built for precision measurements of oscillations. It is likely that both the Gran Sasso laboratory in Italy and the Kamioka mine in Japan will result unsuitable for such future endeavors. Continental locations such as the Baksan Laboratory in Russia, the Heilbron [12] salt mine in Germany, the Homestake mine in South Dakota, the Soudan Mine in Minnesota, and DOE’s Waste Isolation Pilot Plant (WIPP) at Carlsbad (New Mexico) are a priori much more suitable from this point of view. We also note, in passing, that while naval reactors appear to be a problem for precision measurements of reactor neutrinos, their effect is not sufficient to allow reliable and efficient detection of the vessel carrying them, at least for any conceivable detector size.

We now discuss the possibility of using a naval reactor as a mobile source of antineutrinos in oscillation experiments. Variable baseline experiments are known to have a number of advantages over fixed ones. However, as long baseline experiments become larger and require massive shielding, the possibility of moving the detector becomes technically difficult. Neutrino sources also are considered unmovable, in the case of both accelerators and reactors. Since the oscillatory term is proportional to L/E, where L is the baseline and E is the neutrino energy, a change in energy is equivalent to a change in baseline. Indeed, this feature is exploited in accelerator experiments as well as reactor experiments. For the latter, E naturally spans the region 1.8–9 MeV. With some luck, the $\Delta m^2$ for $\bar{\nu}_e - \bar{\nu}_X$ oscillations will be such that KamLAND will observe a spectrum vastly distorted by oscillations. However, the range of energies accessible with a reactor or a single accelerator beam line pointing in a fixed direction is limited. In addition, in the case of reactors, the construction of several detectors at different distances does not

### Table I. Comparison between fixed reactor signal and potential background from naval reactors for KamLAND and BOREXINO.

<table>
<thead>
<tr>
<th>Case</th>
<th>Power (GW_{th})</th>
<th>Det. Mass (kton)</th>
<th>Distance (km)</th>
<th>Flux at 100% power (cm^{-2} s^{-1})</th>
<th>Rate (yr^{-1})</th>
<th>Fraction of Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>KamLAND [5]</td>
<td>175.7</td>
<td>1</td>
<td>~200</td>
<td>$1.3 \times 10^6$</td>
<td>880</td>
<td>⋯</td>
</tr>
<tr>
<td>“Typhoon” sub in Toyama Bay</td>
<td>0.38</td>
<td>1</td>
<td>40</td>
<td>$1.8 \times 10^5$</td>
<td>92</td>
<td>0.10</td>
</tr>
<tr>
<td>Aircraft carrier in Yokosuka</td>
<td>0.84</td>
<td>1</td>
<td>200</td>
<td>$9.5 \times 10^3$</td>
<td>8.1</td>
<td>0.01</td>
</tr>
<tr>
<td>BOREXINO [8]</td>
<td>~520</td>
<td>0.3</td>
<td>~800</td>
<td>$1.9 \times 10^5$</td>
<td>27</td>
<td>⋯</td>
</tr>
<tr>
<td>“Typhoon” sub near Giulianova</td>
<td>0.38</td>
<td>0.3</td>
<td>50</td>
<td>$6.9 \times 10^4$</td>
<td>12</td>
<td>0.46</td>
</tr>
<tr>
<td>Aircraft carrier in Naples</td>
<td>0.84</td>
<td>0.3</td>
<td>200</td>
<td>$9.5 \times 10^3$</td>
<td>1.7</td>
<td>0.06</td>
</tr>
</tbody>
</table>

*aThe distance in this case is calculated to the nearest sea depth of 30 m.*
allow one to cancel the very important systematic error contributions from backgrounds and detector efficiencies. A naval reactor used as an antineutrino source with a detector installed underground near a waterway may come close to the ideal setup. While it appears out of the question to consider using a military vessel for this purpose, a ship from the Russian nuclear icebreaker fleet may well be made available, particularly outside their operating season.

Five “Arktica” class nuclear icebreakers are operated commercially by the Murmansk Shipping Company [16]. While the main mission of the fleet is to guide cargo vessels along the northern coast of Siberia, some of the ships have been employed in a variety of tasks, including taking tourists to the North Pole. Each of these icebreakers is powered by two 100 MW(th) nuclear reactors for a total power of 200 MW(th). The cores are loaded with uranium enriched to 20% in $^{235}\text{U}$ [17] approximately every three years. For reference, in Fig. 1 we compare the antineutrino spectrum produced by a hypothetical reactor built 100% of $^{235}\text{U}$ with the more familiar case of a commercial reactor at the beginning and at the end of a fuel cycle (most commercial reactors at the end of a fuel cycle replace 1/4 to 1/3 of their fuel with uranium enriched to 4% in $^{235}\text{U}$). The spectrum from the icebreaker’s reactors will lay somewhere between those presented in the figure, depending upon the burnup stage of the core. While the exact spectrum will have to be accurately known for an actual experiment, for the purpose of this analysis we will simply assume a 100% $^{235}\text{U}$ core.

The lower power levels available from naval reactors call for a larger detector. We will consider a liquid scintillator detector with 20 ktons fiducial mass (about 30 m in linear dimensions) and a hydrogen to carbon ratio of 2 (as in KamLAND). Scintillation detectors of this size have been discussed [10] and would fit in cavities of the size occupied by SuperKamiokande. At a 2 km distance from the naval reactor, such a detector would observe $3.9 \times 10^3 \bar{\nu}_e \text{ yr}^{-1}$. Such a rate, scaling with $1/L^2$, would reduce to $1.6 \times 10^4 \bar{\nu}_e \text{ yr}^{-1}$ at 10 km and $9.8 \times 10^5 \bar{\nu}_e \text{ yr}^{-1}$ at 40 km. The detector would have to be built at an underground location very far from permanent nuclear installations but accessible by water. An initial extended period of data with no icebreaker in the vicinity would be used to measure the background and other natural phenomena. We can assume that at the end of this period the background will be known with negligible error, as it was in the case of Chooz. The naval reactor would then be brought to the point of closest proximity, that we assume to be 2 km (closer distances are excluded by the need for detector shielding). A 1 month measurement at this distance would give a flux/detector efficiency calibration at the 0.5% level. Measurements

![FIG. 1. Energy spectrum of antineutrinos produced by different types of reactor fuel. The two broken lines correspond to the fuel composition of a commercial power reactor at the beginning and at the end of a fuel cycle. The solid line represents the spectrum for a hypothetical core made of $^{235}\text{U}$ only.](image1)

![FIG. 2. Estimated 95% C.L. errors in $\Delta m^2$ (left panel) and $\tan^2\theta$ (right panel) for tunable baseline experiments compared to the case of a fixed baseline experiment as a function of $\Delta m^2$. The three curves for the tunable baseline case refer to $\tan^2\theta = 0.22$, 0.34, and 0.56, as consistent with the central value and the extremes of the MSW-LMA solar neutrino solution [18]. Only the central value is used for the case of the fixed baseline experiment represented by the shaded region bounded above and below by, respectively, the case of a 100 ton and 1 kton detector.](image2)
would then be performed at a variety of intermediate distances, first in short periods to identify the optimal baseline, then, probably, for an extended period at this optimal place. The calibration run may then be repeated before switching to a second phase in the program, with no reactor, when geological neutrinos and astrophysical sources would be addressed without reactor background. The large size of the detector would be justified also by this second phase of experimentation. It may be appropriate during the lifetime of the detector to periodically bring the icebreaker in for calibrations with neutrinos.

A detailed running strategy for the reactor neutrino oscillation experiment would have to be established, also taking into account the knowledge of the neutrino mixing matrix at the time of the experiment. Here we estimate the sensitivity of this scheme, assuming that data is collected for one year at the optimal baseline for each hypothetical value of $\Delta m^2$. For each pair of $\Delta m^2$ and $\tan^2 \theta$, we then estimate the 95\% C.L. contours of the measurement. In Fig. 2 we plot the projections of such contours (errors in $\Delta m^2$ and $\tan^2 \theta$) as functions of $\Delta m^2$ along with the same quantities for 100 ton [12] and 1 kton detectors at a fixed baseline of 20 km. The three curves for the variable baseline case refer to different mixing angle values. While in the fixed reactor case a systematic error of 2.7\% is used, in the case of the movable reactor we assume a 0.5\% systematic error (consistent with the superior ability to measure backgrounds and efficiency). Appropriate statistical errors are applied to each case.

Clearly the sensitivity of the fixed baseline case is dominated by the oscillation pattern, while the variable baseline case becomes limited by statistics at large distances (small $\Delta m^2$). Compared with the expected performance of KamLAND after three years of data, the case of a mobile reactor contemplated here would give more accurate oscillation parameter measurements for $\Delta m^2$ values above approximately $10^{-4}$ eV$^2$. It should be noted here that the small 0.5\% systematic error assumed here would be dominated by the relative reactor power measurement between calibration and data taking phases. It appears that such a relative error for reactors mounted on icebreakers is currently only about 10\% [17]. Therefore, some engineering would be needed to install precise temperature and flow gauges on the cooling water loops. Commercial nuclear power plants typically measure their power to better than 1\% in absolute terms, so the error we quote should be easily attainable. The possibility of running the reactors at full power with the ship stationary (i.e., without dissipating $\sim 1/3$ of the power in moving the ship) would also have to be investigated. From the cost of a polar trip and the number of accommodations available, it appears that the charter fees of one of these icebreakers should be of the order of one million dollars per month, although it is reasonable to expect substantial savings for a mission, such as the one contemplated here, where no passenger service would be required.

Several general locations would have to be investigated in order to find the optimal location for an experiment of this kind. In general, it appears that the subarctic regions may indeed offer the best chances for underground sites near closed waterways and surrounded by a geophysics that is optimal for the later study of geological neutrinos. Furthermore, these regions are far from permanent nuclear power plants. Ideally, one of the Siberian rivers would ensure that no other nuclear powered vessel approaches the detector, although similar conditions could also be satisfied in a number of Canadian bays accessible from the Arctic Ocean.

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[17] Yu.V. Sivintsev (private communication).